

# *Convolution*

Lecture #6

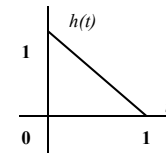
2CT.3 – 8

# Homework

- Convolution Verify your all your results of these convolution problems using Matlab and its conv function.

- Problem (1)

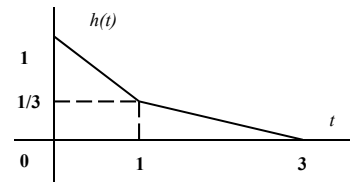
- Assume that a system response is given by the following:



- Sketch the response to a)  $u(t)$ , b)  $u(t)-u(t-a)$  for  $a=0.5$ ,  $a=1$ , and  $a=5$ , and c) evaluate  $e^{-t} u(t)$  at  $t=1$  and  $t=2$

- Problem (2)

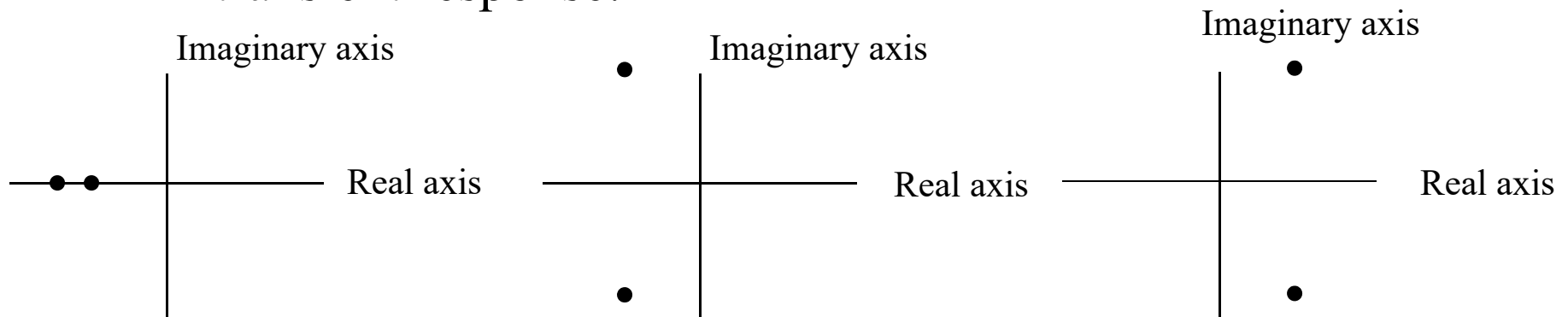
- Assume that a system response is given by the following:



- Evaluate the response to  $te^{-t} u(t)$  at  $t=1$  and  $t=3$

# Homework

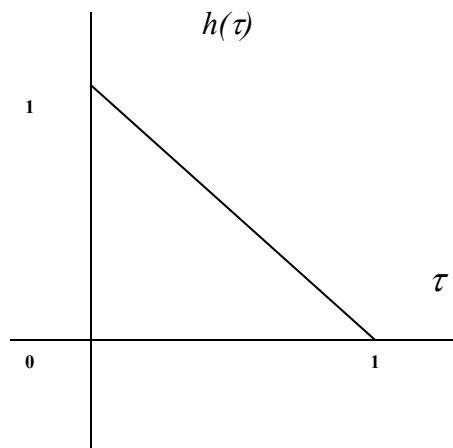
- Stability
  - Determine the stability of the following systems with poles in the complex plane, describe the form of the transient response:



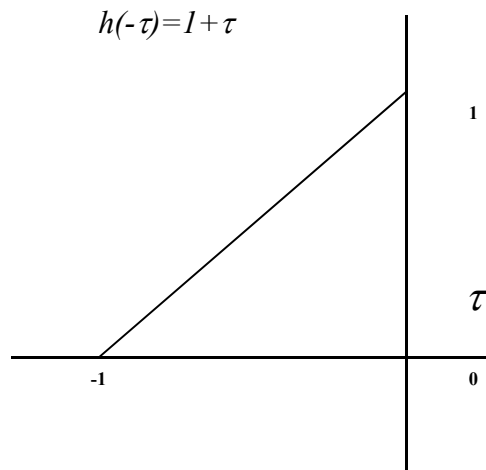
- 2CT.3.1, 2CT.3.2

# Homework Answers #1

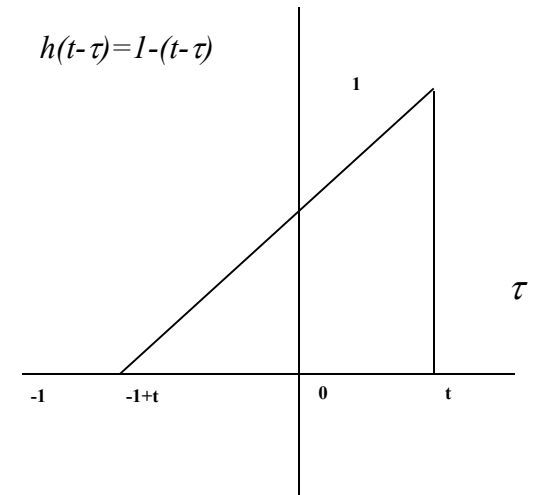
- Convolution
  - Problem (1)
    - Assume that a system response is given by the following:



$$h(\tau) = (1 - \tau) \text{ for } 0 < \tau < 1$$



$$h(-\tau) = (1 + \tau) \text{ for } -1 < \tau < 0$$

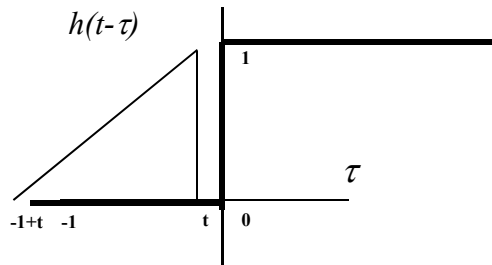


$$h(t - \tau) = [1 - (t - \tau)] \text{ for } -(1-t) < \tau < t$$

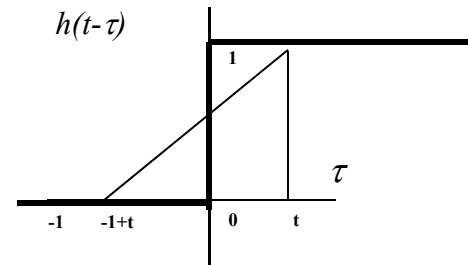
# Homework Answers #2

- Convolution
  - Problem (1)
    - Sketch the response to a)  $u(t)$

$$a) C = \int [1 - (t - \tau)]u(t - \tau)u(\tau)d\tau$$



$$t < 0, C = 0$$



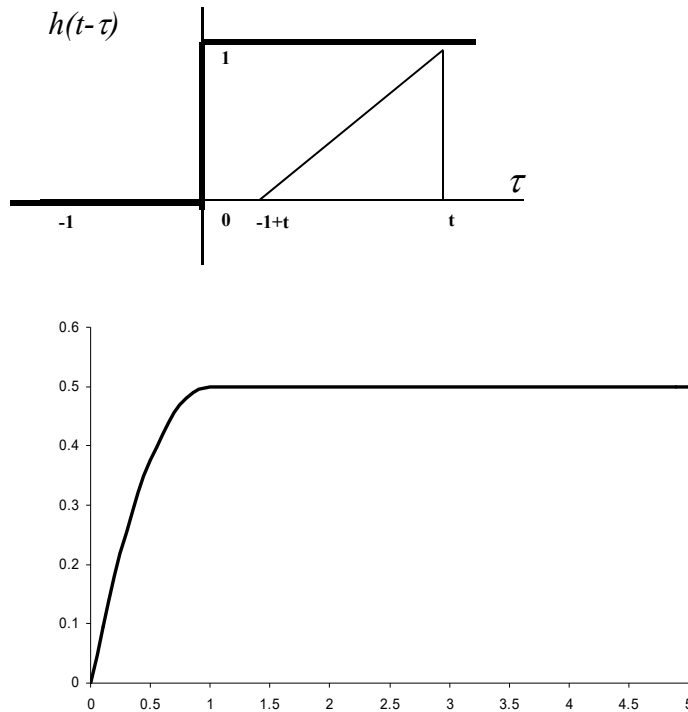
$$0 < t < 1$$

$$\begin{aligned} C &= \int_0^t 1 * [1 - (t - \tau)] d\tau = \frac{[1 - (t - \tau)]^2}{2} \Big|_0^t \\ &= \frac{1}{2} - \frac{[1 - t]^2}{2} = \frac{1}{2} [1 - (1 - t)^2] \\ &= \frac{1}{2} [1 - 1 + 2t - t^2] = t - \frac{t^2}{2} \end{aligned}$$

# Homework Answers #3

- Convolution
  - Problem (1)
    - Sketch the response to a)  $u(t)$

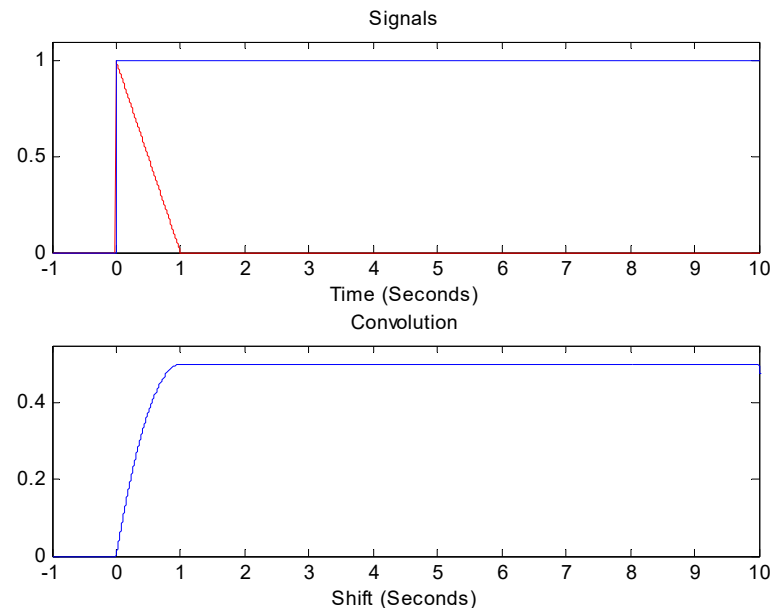
$$a) C = \int [1 - (t - \tau)]u(t - \tau)u(\tau)d\tau$$



$$\begin{aligned} t > 1, C &= \int_{-1+t}^t 1 \times [1 - (t - \tau)] d\tau \\ &= \frac{[1 - (t - \tau)]^2}{2} \Big|_{-1+t}^t \\ &= \frac{1}{2} - \frac{0}{2} = \frac{1}{2} \end{aligned}$$

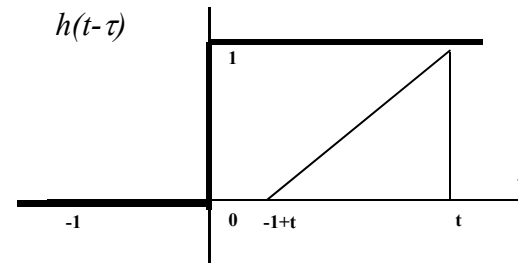
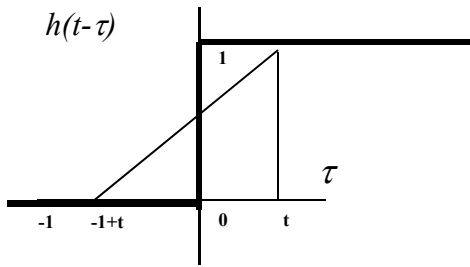
# Matlab Code

```
clear all;
endpulse=20;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0)&(n<=endpulse);
pulse=1*pulser;
tripulse=(n>=0)&(n<=1);
tri=(1-n).*tripulse;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
title('Convolution');
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```



# Homework Answers #2

- Convolution
  - Problem (1) Alternative integration
    - Sketch the response to a)  $u(t)$



$$0 < t < 1$$

$$C = \int_0^t 1 * [1 - (t - \tau)] d\tau = \left[ \tau + \frac{\tau^2}{2} - t\tau \right]_0^t$$

$$= t + \frac{t^2}{2} - t^2 = t - \frac{t^2}{2}$$

$$t > 1, C = \int_{-1+t}^t 1 * [1 - (t - \tau)] d\tau$$

$$= \tau + \frac{\tau^2}{2} - t\tau \Big|_{-1+t}^t = t + \frac{t^2}{2} - t^2 - [(t-1) + \frac{(t-1)^2}{2} - (t-1)t]$$

$$= t + \frac{t^2}{2} - t^2 + [(-t+1) - \frac{(t-1)^2}{2} + (t-1)t]$$

$$= t + \frac{t^2}{2} - t^2 + [-t+1 - \frac{t^2}{2} + \frac{2t}{2} - \frac{1}{2} + t^2 - t]$$

$$= t - \frac{t^2}{2} + [\frac{t^2}{2} + \frac{1}{2} - t] = \frac{1}{2}$$

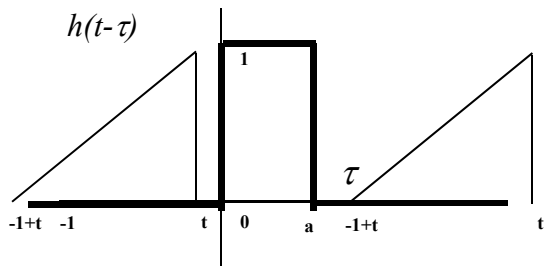


# Homework Answers #4

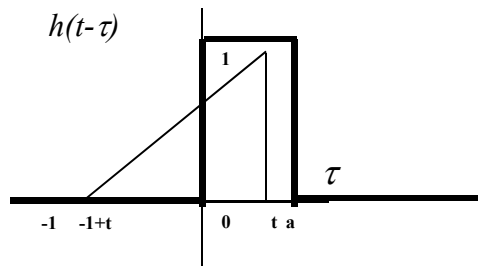
- Convolution
  - Problem (1)
    - Sketch the response to b)  $u(t)-u(t-a)$  for  $a=0.5$

$$b) C = \int [1 - (t - \tau)]u(t - \tau)u(\tau)d\tau + \int [1 - (t - \tau)]u(t - \tau)u(\tau - a)d\tau$$

for  $a \leq 1$



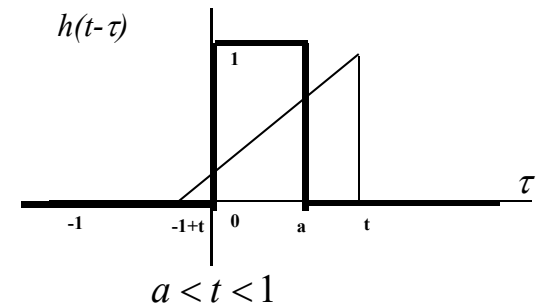
$t < 0$  &  $t > a+1$ ,  
 $C=0$



$0 < t < a$

$$C = \int_0^t 1 * [1 - (t - \tau)]d\tau = \frac{[1 - (t - \tau)]^2}{2} \Big|_0^t$$

$$= \frac{1}{2} - \frac{[1 - t]^2}{2} = \frac{1}{2}[1 - (1 - t)^2]$$



$a < t < 1$

$$C = \int_0^a 1 * [1 - (t - \tau)]d\tau$$

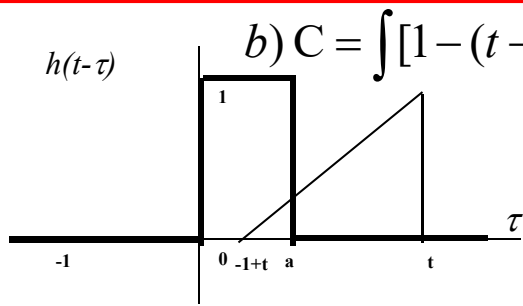
$$= \frac{[1 - (t - \tau)]^2}{2} \Big|_0^a$$

$$= \frac{[1 - (t - a)]^2}{2} - \frac{[1 - t]^2}{2}$$

$$= \frac{2a - 2at + a^2}{2}$$

# Homework Answers #5

- Convolution
  - Problem (1)
    - Sketch the response to b)  $u(t)-u(t-a)$  for  $a=0.5$



$$t < a+1$$

$$\begin{aligned}
 C &= \int_{-1+t}^a 1 * [1-(t-\tau)] d\tau \\
 &= \frac{[1-(t-\tau)]^2}{2} \Big|_{-1+t}^a \\
 &= \frac{[1-(t-a)]^2}{2} - 0 \\
 &= \frac{[1-(t-a)]^2}{2}
 \end{aligned}$$

$$b) C = \int [1-(t-\tau)]u(t-\tau)u(\tau)d\tau + \int [1-(t-\tau)]u(t-\tau)u(\tau-a)d\tau$$

$$\text{for } a \leq 1$$

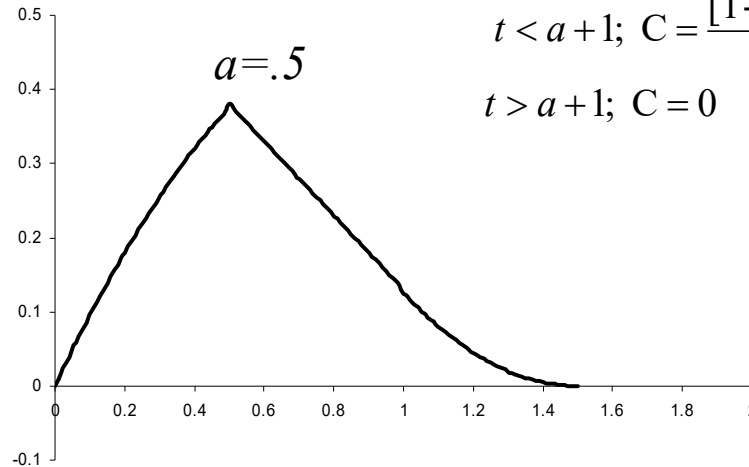
$$t < 0; C = 0$$

$$0 < t < a; C = \frac{1}{2}[1-(1-t)^2]$$

$$a < t < 1; C = \frac{2a-2at+a^2}{2}$$

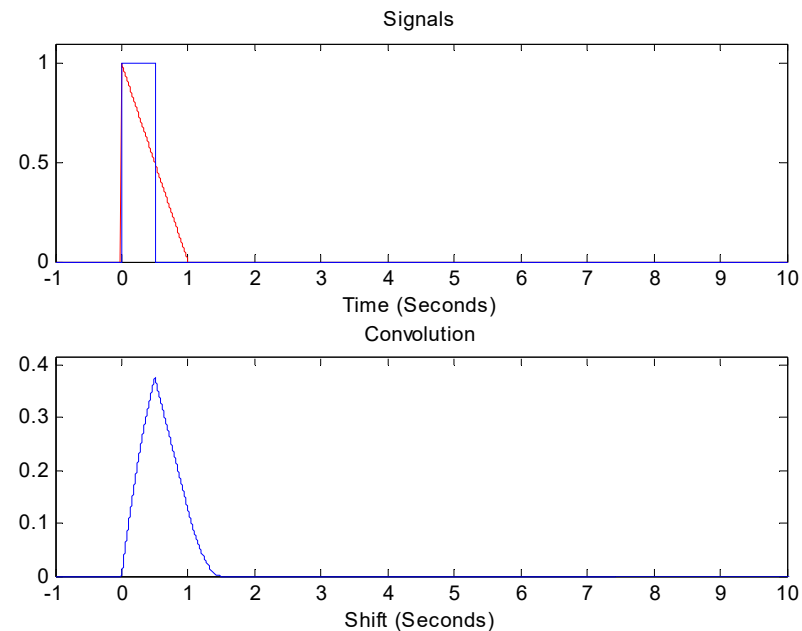
$$t < a+1; C = \frac{[1-(t-a)]^2}{2}$$

$$t > a+1; C = 0$$



# Matlab Code

```
clear all;
endpulse=.5;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0)&(n<=endpulse);
pulse=1*pulser;
tripulse=(n>=0)&(n<=1);
tri=(1-n).*tripulse;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
title('Convolution');
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```



# Homework Answers #6

- Convolution
  - Problem (1):
    - Sketch the response to b)  $u(t)-u(t-a)$  for  $a=1$

$$b) C = \int [1-(t-\tau)]u(t-\tau)u(\tau)d\tau + \int [1-(t-\tau)]u(t-\tau)u(\tau-a)d\tau$$

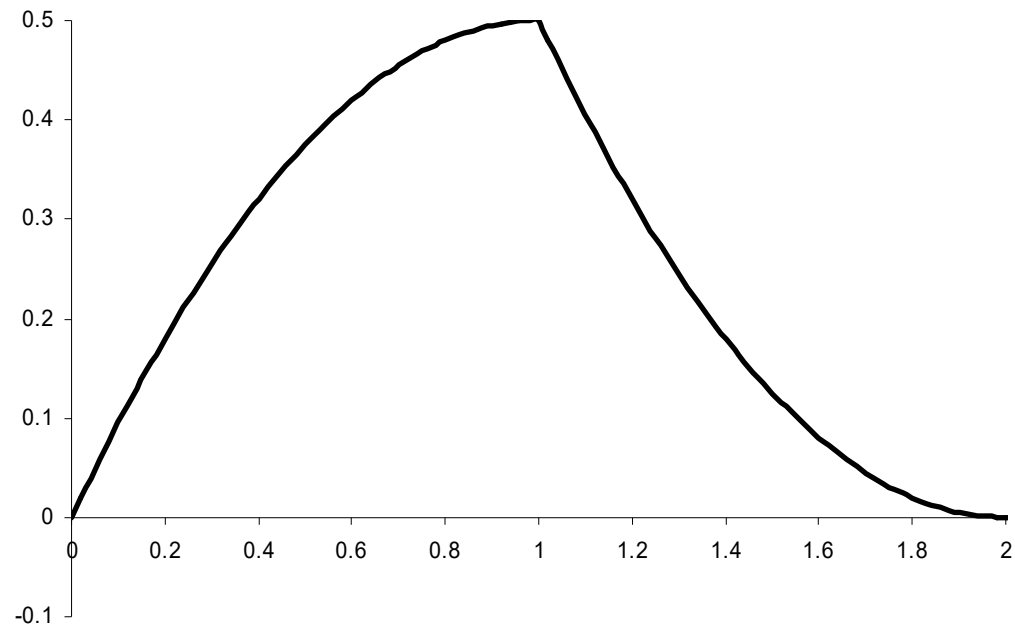
for  $a \leq 1$

$$t < 0; C = 0$$

$$0 < t < 1; C = \frac{1}{2}[1-(1-t)^2]$$

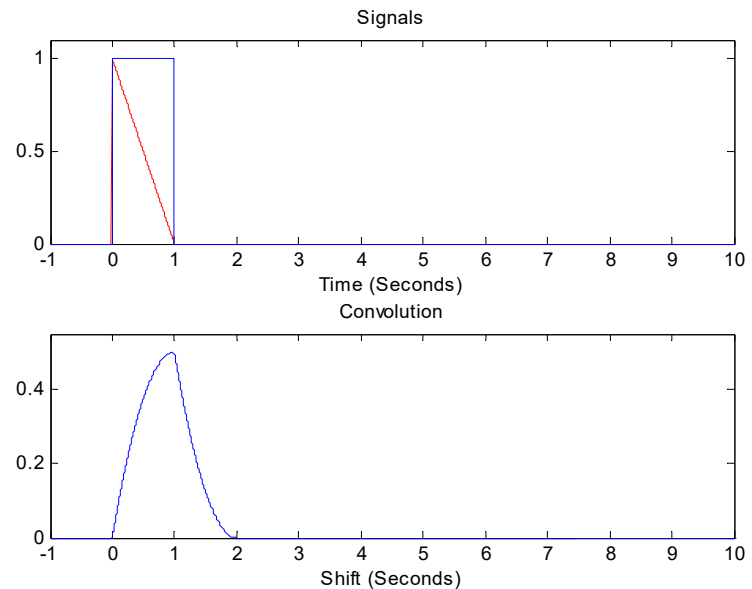
$$t < 2; C = \frac{[1-(t-1)]^2}{2}$$

$$t > 2; C = 0$$



# Matlab Code

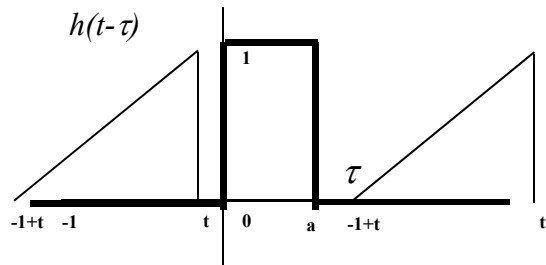
```
clear all;
endpulse=1;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0)&(n<=endpulse);
pulse=1*pulser;
tripulse=(n>=0)&(n<=1);
tri=(1-n).*tripulse;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
title('Convolution');
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```



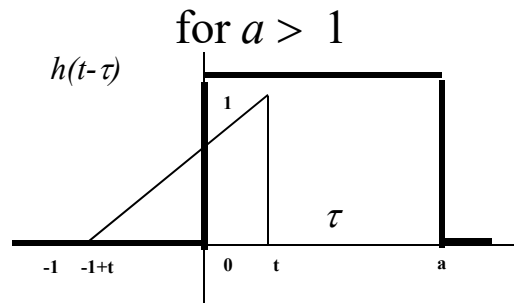
# Homework Answers #7

- Convolution
  - Problem (1)
    - Sketch the response to b)  $u(t)-u(t-a)$  for  $a=5$

$$b) C = \int [1 - (t - \tau)]u(t - \tau)u(\tau)d\tau + \int [1 - (t - \tau)]u(t - \tau)u(\tau - a)d\tau$$

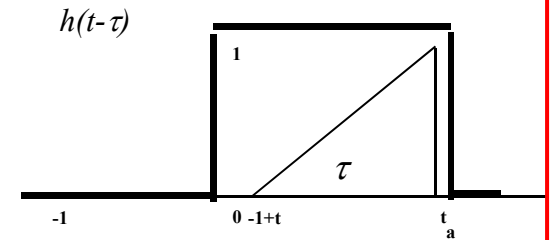


$$t < 0 \text{ \& \; } t > a+1, \\ C=0$$



$$0 < t < a < 1$$

$$C = \int_0^t 1 * [1 - (t - \tau)]d\tau = \left. \frac{[1 - (t - \tau)]^2}{2} \right|_0^t \\ = \frac{1}{2} - \frac{[1 - t]^2}{2} = \frac{1}{2}[1 - (1 - t)^2]$$



$$1 < t < a$$

$$C = \int_{-1+t}^t 1 * [1 - (t - \tau)]d\tau \\ = \left. \frac{[1 - (t - \tau)]^2}{2} \right|_{-1+t}^t \\ = \frac{1}{2} - 0 \\ = \frac{1}{2}$$

# Homework Answers #8

- Convolution
  - Problem (1) :
    - Sketch the response to b)  $u(t)-u(t-a)$  for  $a=5$

$a < t < a+1$

b)  $C = \int [1 - (t - \tau)]u(t - \tau)u(\tau)d\tau + \int [1 - (t - \tau)]u(t - \tau)u(\tau - a)d\tau$

for  $a > 1$

$t < 0; C = 0$

$0 < t < a < 1; C = \frac{1}{2}[1 - (1-t)^2]$

$1 < t < a; C = \frac{1}{2}$

$t > a; C = \frac{[1 - (t-a)]^2}{2}$

$t > a+1; C = 0$

$$C = \int_{-1+t}^a 1 * [1 - (t - \tau)] d\tau$$

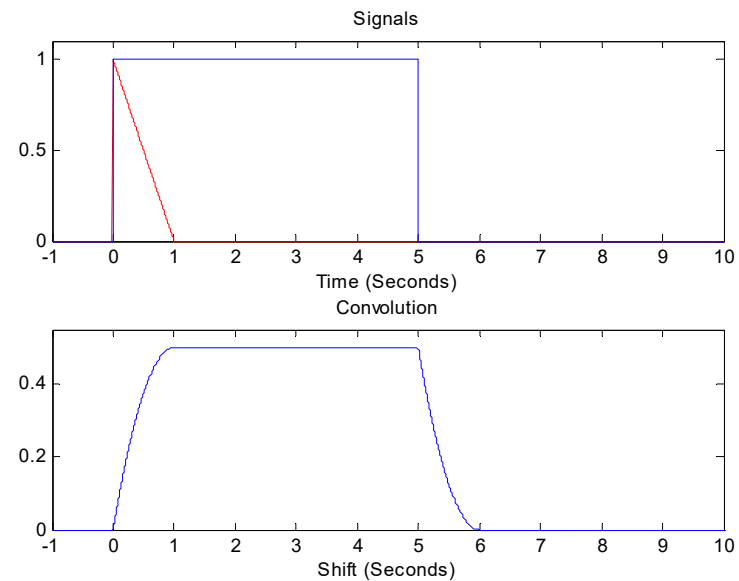
$$= \frac{[1 - (t - \tau)]^2}{2} \Big|_{-1+t}^a$$

$$= \frac{[1 - (t - a)]^2}{2} - 0$$

$$= \frac{[1 - (t - a)]^2}{2}$$

# Matlab Code

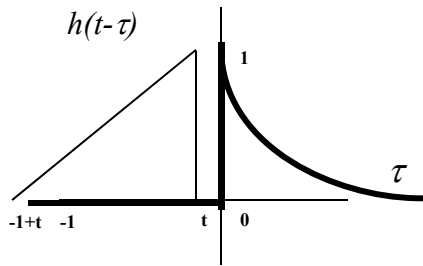
```
clear all;
endpulse=5;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0)&(n<=endpulse);
pulse=1*pulser;
tripulse=(n>=0)&(n<=1);
tri=(1-n).*tripulse;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
title('Convolution');
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```



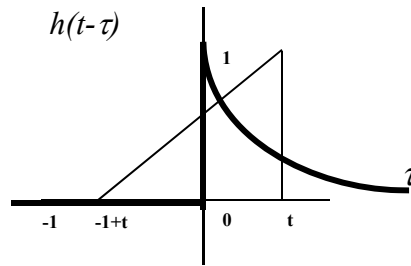


# Homework Answers #9

- Convolution
  - Problem (1)
    - c) evaluate  $e^{-t} u(t)$  at  $t=1$  and  $t=2$



$$t < 0, C = 0$$



$$0 < t < 1, C = \int_0^t e^{-\tau} \times [1 - (t - \tau)] d\tau$$

$$= -e^{-\tau} [1 - (t - \tau)] - e^{-\tau} \Big|_0^t$$

$$= (-e^{-t} [1 - (t - t)] - e^{-t}) - (-e^{-0} [1 - (t - 0)] - e^{-0})$$

$$= (-e^{-t} - e^{-t}) - (-1 \times [1 - t] - 1)$$

$$C(t) = 2 - t - 2e^{-t}; 0 < t < 1$$

$$C(1) = 2 - 1 - 2e^{-1} = .264$$

$$c) C = \int [1 - (t - \tau)] u(t - \tau) e^{-t} u(\tau) d\tau \quad \text{Integration by parts:}$$

$$\int v \frac{du}{d\tau} d\tau = uv - \int u \frac{dv}{d\tau} d\tau$$

$$v = 1 - (t - \tau); dv = d\tau$$

$$\frac{du}{d\tau} = e^{-\tau}; u = -e^{-\tau}$$

$$\int [1 - (t - \tau)] e^{-\tau} d\tau$$

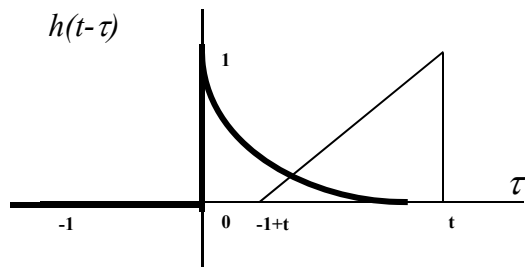
$$= -e^{-\tau} [1 - (t - \tau)] + \int e^{-\tau} \times 1 d\tau$$

$$= -e^{-\tau} [1 - (t - \tau)] - e^{-\tau} + C$$

# Homework Answers #10

- Convolution
  - Problem (1)
    - c) evaluate  $e^{-t} u(t)$  at  $t=1$  and  $t=2$

$$c) C = \int [1 - (t - \tau)] u(t - \tau) e^{-\tau} u(\tau) d\tau$$



$$t > 1, C = \int_{-1+t}^t e^{-\tau} \times [1 - (t - \tau)] d\tau$$

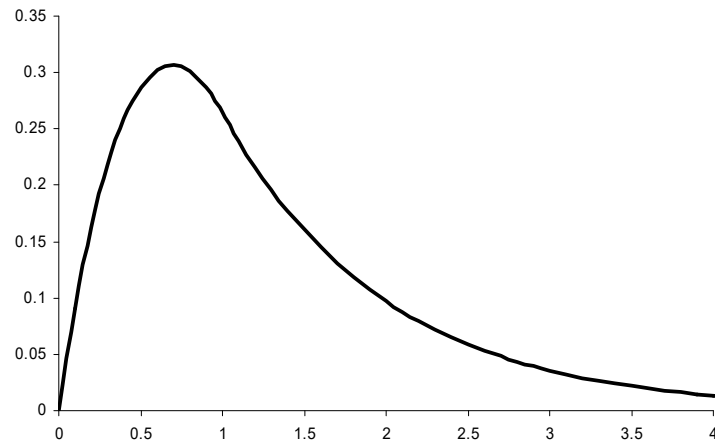
$$= -e^{-\tau} [1 - (t - \tau)] - e^{-\tau} \Big|_{-1+t}^t$$

$$= (-e^{-t} [1 - (t - t)] - e^{-t}) - (-e^{1-t} [1 - (t - [-1 + t])]) - e^{1-t}$$

$$= (-e^{-t} [1 - (0)] - e^{-t}) - (-e^{1-t} [0] - e^{1-t})$$

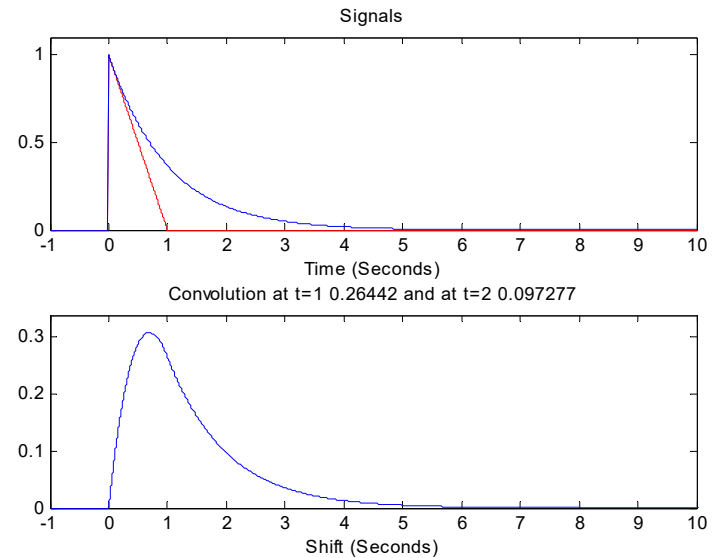
$$= e^{1-t} - 2e^{-t}; t > 1,$$

$$= e^{-1} - 2e^{-2} = .097$$



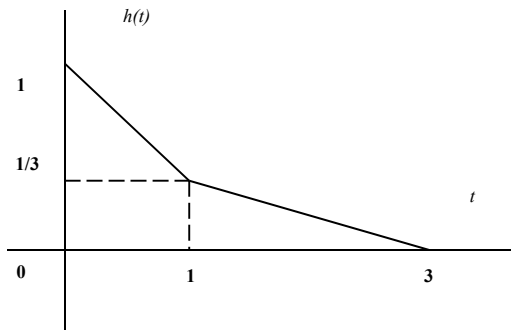
# Matlab Code

```
clear all;
endpulse=20;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0);
pulse=exp(-n).*pulser;
tripulse=(n>=0)&(n<=1);
tri=(1-n).*tripulse;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
for i=1:length(nn)
    if nn(i)==1
        c1=i;
    end
    if nn(i)==2
        c2=i;
    end
end
title(['Convolution at t=1 ',num2str(c(c1)),'] and at t=2 ',num2str(c(c2))]);
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```

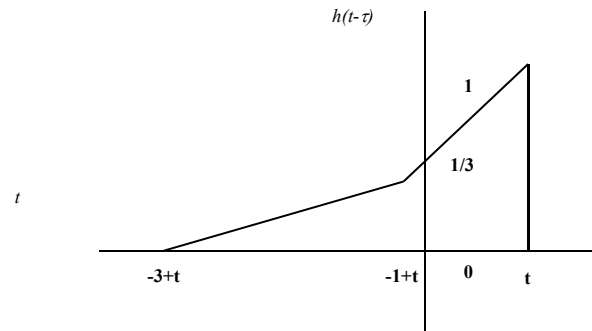


# Homework Answers #11

- Convolution
  - Problem (2)
    - Assume that a system response is given by the following:
    - Evaluate the response to  $te^{-t} u(t)$  at  $t=1$  and  $t=3$



$$\begin{aligned}
 h(\tau) &= \left(1 - \frac{2}{3}\tau\right); \quad 0 < \tau < 1 \\
 &= \frac{1}{6}(3 - \tau); \quad 1 < \tau < 3 \\
 &= 0; \text{ elsewhere}
 \end{aligned}$$



$$\begin{aligned}
 h(t - \tau) &= \left[1 - \frac{2}{3}(t - \tau)\right]; \quad 0 < t - \tau < 1, -1 + t < \tau < t \\
 &= \frac{1}{6}[3 - (t - \tau)]; \quad 1 < t - \tau < 3, -3 + t < \tau < -1 + t \\
 &= 0; \text{ elsewhere}
 \end{aligned}$$

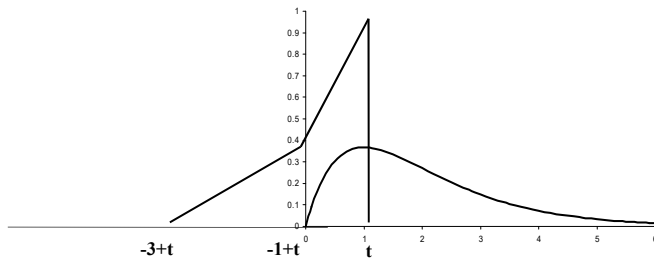
# Homework Answers #12

- Convolution
  - Problem (2)
    - Assume that a system response is given by the following:
    - Evaluate the response to  $te^{-t} u(t)$  at  $t=1$  and  $t=3$

$$h(t-\tau) = \left[1 - \frac{2}{3}(t-\tau)\right]; 0 < t-\tau < 1, -1+t < \tau < t$$

$$= \frac{1}{6}[3 - (t-\tau)]; 1 < t-\tau < 3, -3+t < \tau < -1+t$$

$$= 0; \text{ elsewhere}$$



$$C = \int_0^t \tau e^{-\tau} h(t-\tau) d\tau$$

$$= \int_0^t \tau \left[1 - \frac{2}{3}(t-\tau)\right] e^{-\tau} d\tau$$

$$= \int_0^1 \tau \left[1 - \frac{2}{3}(1-\tau)\right] e^{-\tau} d\tau$$

$$= \int_0^1 \tau \left[\frac{1}{3} + \frac{2}{3}\tau\right] e^{-\tau} d\tau$$

$$C = \int_0^1 \left[\frac{2}{3}\tau^2 + \frac{1}{3}\tau\right] e^{-\tau} d\tau$$

## Homework Answers #13

$$\begin{aligned}C &= \int_0^1 \left[ \frac{2}{3} \tau^2 + \frac{1}{3} \tau \right] e^{-\tau} d\tau \\&= \left\{ \frac{2}{3} (\tau^2 + 2\tau + 2) + \frac{1}{3} (\tau + 1) \right\} (-e^{-\tau}) \Big|_0^1 \\&= \left\{ \frac{2}{3} (1 + 2 + 2) + \frac{1}{3} (1 + 1) \right\} (-e^{-1}) \\&\quad - \left\{ \frac{2}{3} (0 + 0 + 2) + \frac{1}{3} (0 + 1) \right\} (-e^{-0}) \\&= \frac{5}{3} - \left[ \frac{12}{3} (-e^{-1}) \right] \\&= .195\end{aligned}$$

Integration by parts

$$\int_a^b t^2 e^{-t} dt$$

$$u = t^2; du = 2t dt$$

$$dv = e^{-t} dt; v = -e^{-t}$$

$$\int_a^b t^2 e^{-t} dt = t^2 (-e^{-t}) \Big|_a^b - (-2) \int_a^b t e^{-t} dt$$

$$= t^2 (-e^{-t}) \Big|_a^b - (-2) [(t+1)(-e^{-t})] \Big|_a^b$$

$$= (t^2 + 2t + 2)(-e^{-t}) \Big|_a^b$$

$$\int_a^b t e^{-t} dt$$

$$u = t; du = 1 dt$$

$$dv = e^{-t} dt; v = -e^{-t}$$

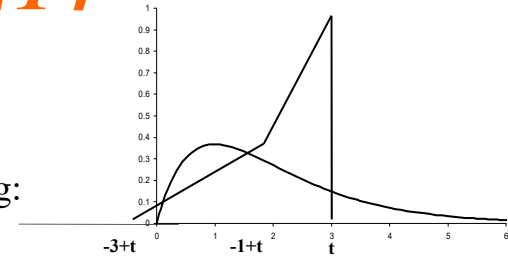
$$\int_a^b t e^{-t} dt = t(-e^{-t}) \Big|_a^b - \int_a^b (1)(-e^{-t}) dt$$

$$= t(-e^{-t}) \Big|_a^b - e^{-t} \Big|_a^b$$

$$= (t+1)(-e^{-t}) \Big|_a^b$$

# Homework Answers #14

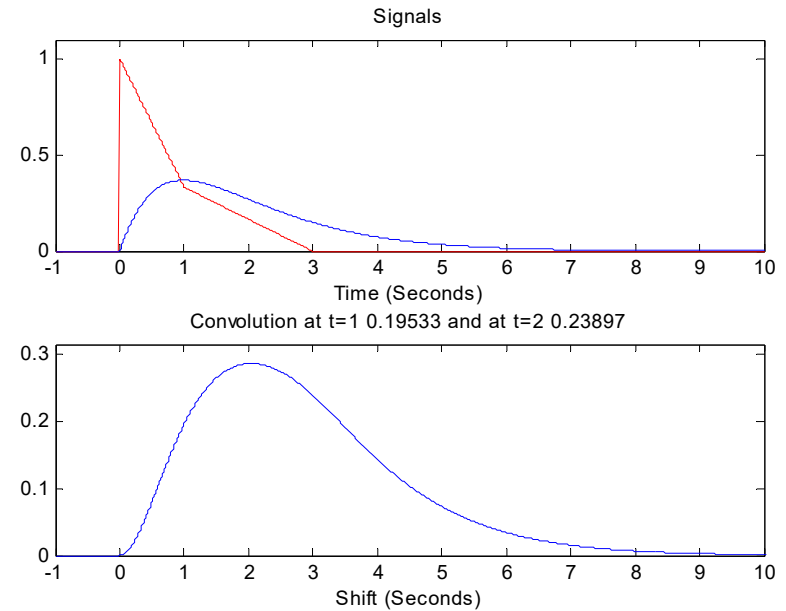
- Convolution
  - Problem (2)
    - Assume that a system response is given by the following:
    - Evaluate the response to  $te^t u(t)$  at  $t=1$  and  $t=3$



$$\begin{aligned}
 C &= \int_0^t \tau e^{-\tau} h(t-\tau) d\tau \\
 &= \int_{-1+t}^t \tau \left[1 - \frac{2}{3}(t-\tau)\right] e^{-\tau} d\tau \\
 &\quad + \int_0^{-1+t} \frac{1}{6} \tau [3 - (t-\tau)] e^{-\tau} d\tau \\
 &= \int_2^3 \tau \left[1 - \frac{2}{3}(3-\tau)\right] e^{-\tau} d\tau \\
 &\quad + \int_0^2 \frac{1}{6} \tau [3 - (3-\tau)] e^{-\tau} d\tau \\
 &= \int_2^3 \left[\frac{2}{3}\tau^2 - \tau\right] e^{-\tau} d\tau + \int_0^2 \frac{\tau^2}{6} e^{-\tau} d\tau \\
 &= \frac{2}{3} (\tau^2 + 2\tau + 2)(-e^{-\tau}) \Big|_2^3 - (\tau + 1)(-e^{-\tau}) \Big|_2^3 + \frac{1}{6} (\tau^2 + 2\tau + 2)(-e^{-\tau}) \Big|_0^2 \\
 &= \left\{ \frac{2}{3} (9 + 6 + 2)(-e^{-3}) - (3 + 1)(-e^{-3}) + \frac{1}{6} (4 + 4 + 2)(-e^{-2}) \right\} \\
 &\quad - \left\{ \frac{2}{3} (4 + 4 + 2)(-e^{-2}) - (2 + 1)(-e^{-2}) + \frac{1}{6} (0 + 0 + 2)(-e^{-0}) \right\} \\
 &= \left\{ \frac{22}{3} (-e^{-3}) + \frac{5}{3} (-e^{-2}) \right\} - \left\{ \frac{11}{3} (-e^{-2}) + \frac{1}{3} (-e^{-0}) \right\} \\
 &= \frac{1}{3} \{1 + 6e^{-2} - 22e^{-3}\} \\
 &= .239
 \end{aligned}$$

# Matlab Code

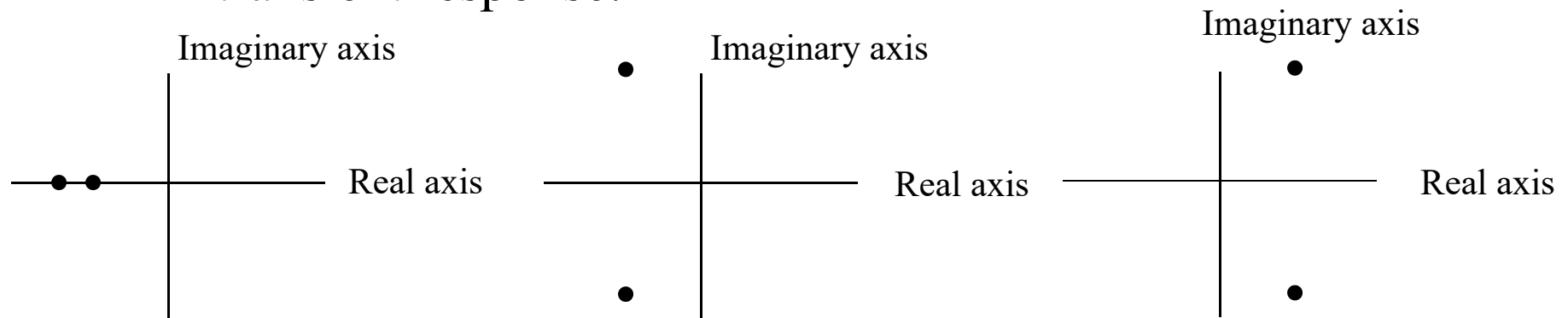
```
clear all;
endpulse=20;
ts=.001;
endpoint=10;
n=-endpoint:ts:endpoint;
nn=-endpoint*2:ts:endpoint*2;
pulser=(n>=0);
pulsers=exp(-n).*pulser;
pulse=n.*pulsers;
tripulse=(n>=0)&(n<=1);
tri1=(1-2*n/3).*tripulse;
tripulse2=(n>1)&(n<=3);
tri2=1/6*(3-n).*tripulse2;
tri=tri1+tri2;
subplot(2,1,1)
plot(n,tri,'r',n,pulse,'b');
title('Signals');
xlabel('Time (Seconds)');
axis([-1 10 min([min(tri) min(pulse)]) 1.1*max([max(tri) max(pulse)])]);
c=conv(pulse,tri)*ts;
subplot(2,1,2)
plot(nn,c);
for i=1:length(nn)
    if nn(i)==1
        c1=i;
    end
    if nn(i)==3
        c2=i;
    end
end
end
title(['Convolution at t=1 ',num2str(c(c1)),' and at t=2 ',num2str(c(c2))]);
xlabel('Shift (Seconds)');
axis([-1 10 min(c) 1.1*max(c)]);
```





## Homework Answers #15

- Stability
  - Determine the stability of the following systems with poles in the complex plane, describe the form of the transient response:



Stable  
Overdamped  
system

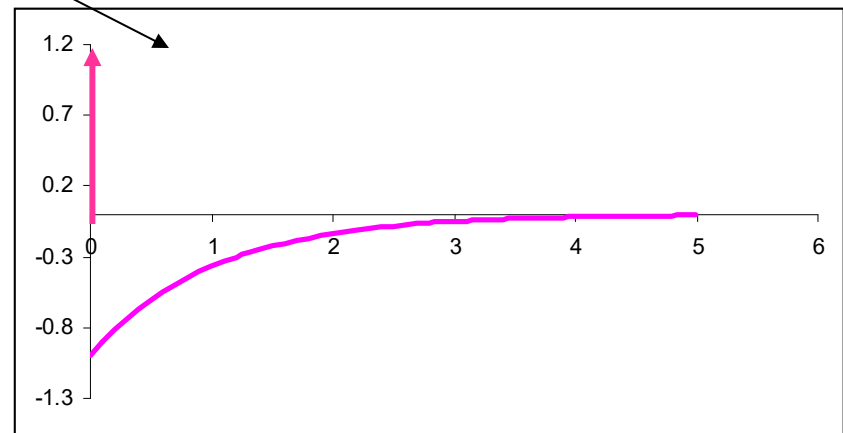
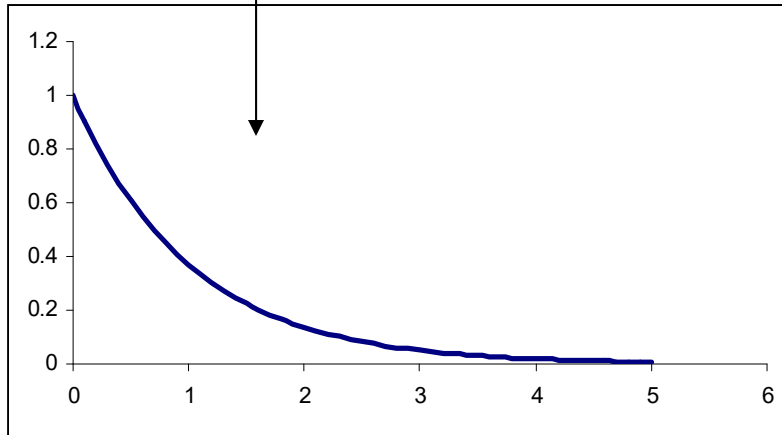
Stable  
Underdamped  
system

Unstable system  
Oscillatory with  
Exponentially  
increasing Amplitude

# 2CT3.1

$$x(t) = e^{-t/\tau} u(t)$$

$$y(t) = \frac{dx(t)}{dt} = \frac{d\{e^{-t/\tau} u(t)\}}{dt} = u(t) \frac{d\{e^{-t/\tau}\}}{dt} + e^{-t/\tau} \frac{d\{u(t)\}}{dt}$$
$$= -\frac{u(t)e^{-t/\tau}}{\tau} + e^{-t/\tau} \delta(t) = e^{-0/\tau} \delta(t) - \frac{1}{\tau} e^{-t/\tau} u(t) = \delta(t) - \frac{1}{\tau} e^{-t/\tau} u(t)$$



## 2CT3.2

$$y(t) = \frac{1}{\tau} \int_{t-\tau}^t x(\lambda) d\lambda$$

$$h(t) = \frac{1}{\tau} \int_{t-\tau}^t \delta(\lambda) d\lambda;$$

Note:

$$u(t) = \int_{-\infty}^t \delta(\lambda) d\lambda$$

$$h(t) = \frac{1}{\tau} \int_{t-\tau}^t \delta(\lambda) d\lambda = \frac{1}{\tau} \int_{-\infty}^t \delta(\lambda) d\lambda - \frac{1}{\tau} \int_{-\infty}^{t-\tau} \delta(\lambda) d\lambda$$

$$= \frac{1}{\tau} u(t) - \frac{1}{\tau} u(t - \tau)$$

